One Step Forward, Two Steps Back: Vector Potential in SPMHD



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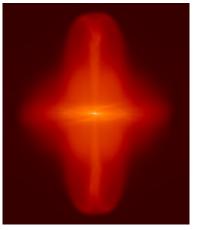


SPMHD simulates magnetohydrodynamics (magnetized fluids).Magnetic field is coupled to the hydrodynamic equations.

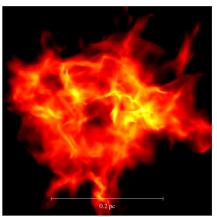
$$\frac{\mathrm{d}v^{i}}{\mathrm{d}t} = \frac{1}{\rho} \frac{\partial S^{ij}}{\partial x^{j}} \qquad S^{ij} = -\delta^{ij} \left(P + \frac{B^{2}}{2\mu_{0}} \right) + \frac{B^{i}B^{j}}{\mu_{0}}$$
$$\frac{\mathrm{d}\mathbf{B}}{\mathrm{d}t} = -\left(\mathbf{B} \cdot \nabla \right) \mathbf{v} + \mathbf{B} \left(\nabla \cdot \mathbf{v} \right)$$

 $\nabla \cdot \mathbf{B} = 0$

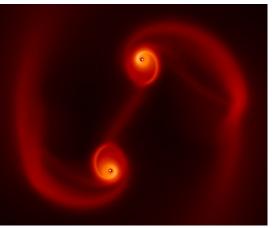
Star Formation



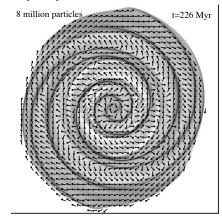
Star Cluster Formation





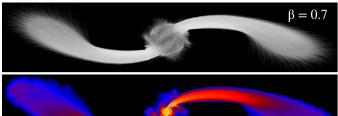


Milky Way

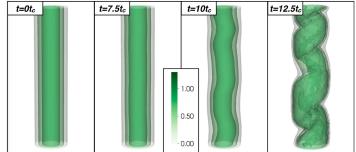


Price, **Tricco** & Bate (2012); Wurster, Price, Bate (2016); Liptai et al (2017); Dobbs, Price, Pettitt, Bate, **Tricco** (2016); Bonnerot et al (2017); Vela Vela et al (2019); **Tricco** Price & Federrath (2016)

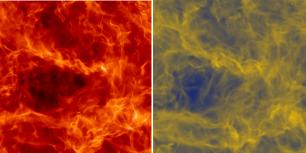
Tidal Disruption Events



Magnetically Confined Plasmas



Magnetized Turbulence



The primary challenge in simulating magnetized fluids with SPH is the divergence-free condition.

$\nabla \cdot \mathbf{B} = 0$

For the past decade, SPMHD simulations have used **constrained** hyperbolic divergence cleaning (Tricco, Price 2012; Tricco, Price, Bate 2016).

Constrained cleaning typically provides a 10x reduction in divergence error, and keeps average error around the ~1% level.

Goal: Create an exactly divergence-free SPMHD

Formulating the magnetic field in terms of the Vector Potential is a logical choice.

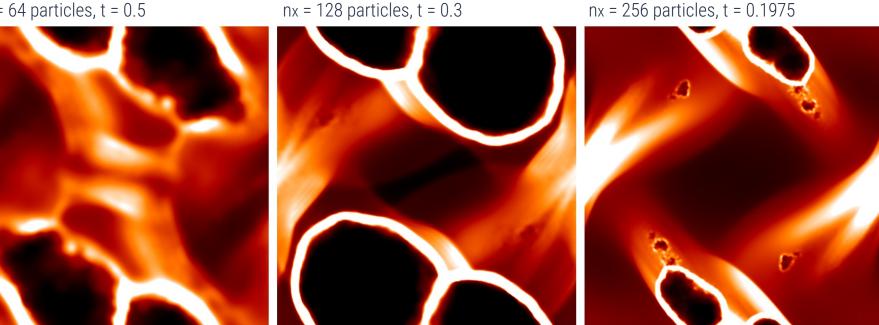
$\mathbf{B}=\nabla\!\times\!\mathbf{A}$

- The divergence of the curl is zero.
- Guaranteed to create a divergence-free magnetic field by construction.

Price (2010) investigated the vector potential, finding severe numerical issues.

Orszag-Tang Vortex with Vector Potential





Start with the induction equation and use $\mathbf{B} =
abla imes \mathbf{A}$.

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{v} \times \mathbf{B}) \qquad \longrightarrow \qquad \frac{\partial \mathbf{A}}{\partial t} = \mathbf{v} \times (\nabla \times \mathbf{A}) + \nabla \phi_t$$

Choose the gauge $\phi = -\mathbf{v} \cdot \mathbf{A}$ (constant of integration) yields the Galiliean invariant discretised equations:

$$\frac{\mathrm{d}A_a^i}{\mathrm{d}t} = \frac{A_a^j}{\Omega_a \rho_a} \sum_b m_b \left(v_a^j - v_b^j \right) \frac{\partial W_{ab}(h_a)}{\partial x_a^i}$$

Our new approach is to express the vector potential in **integral form**.

$$\frac{\partial \mathbf{A}}{\partial t} = \mathbf{v} \times (\nabla \times \mathbf{A}) \longrightarrow \frac{\mathrm{d}}{\mathrm{d}t} \int_{V} \mathbf{A} \mathrm{d}V = \int_{v} \mathbf{v} \times \mathbf{B} \mathrm{d}V + \int_{\partial V} \mathbf{A} \mathbf{v} \cdot \mathrm{d}S$$
$$= \int_{v} \mathbf{v} \times \mathbf{B} \mathrm{d}V + \int_{V} \nabla_{j} (\mathbf{A} \mathbf{v}^{j}) \mathrm{d}V.$$

Which discretized into SPMHD using $\phi = -\mathbf{v} \cdot \mathbf{A}$ yields

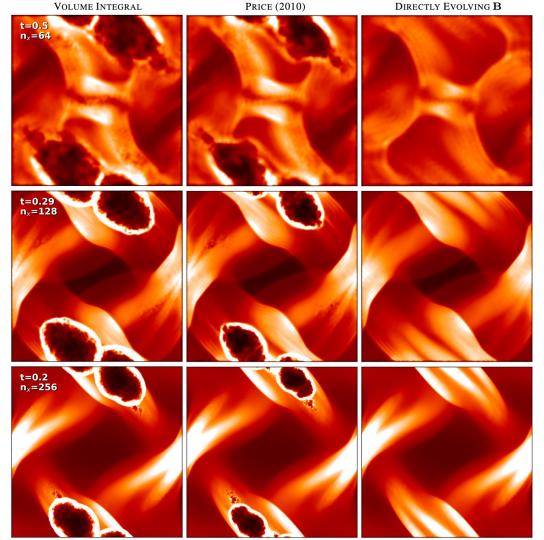
$$\begin{split} \frac{\mathrm{d}A_a^i}{\mathrm{d}t} = & \frac{A_a^j}{\Omega_a \rho_a} \sum_b m_b \left(v_a^j - v_b^j \right) \frac{\partial W_{ab}(h_a)}{\partial x_a^i} \\ &+ \frac{1}{\Omega_a \rho_a} \sum_b m_b \left(A_a^i - A_b^i \right) \left[(v_a^j - v_b^j) \frac{\partial W_{ab}(h_a)}{\partial x_a^j} \right] \end{split}$$

Price (2010) formulation

$$\frac{\mathrm{d}A_a^i}{\mathrm{d}t} = \frac{A_a^j}{\Omega_a \rho_a} \sum_b m_b \left(v_a^j - v_b^j \right) \frac{\partial W_{ab}(h_a)}{\partial x_a^i}$$

New integral formulation

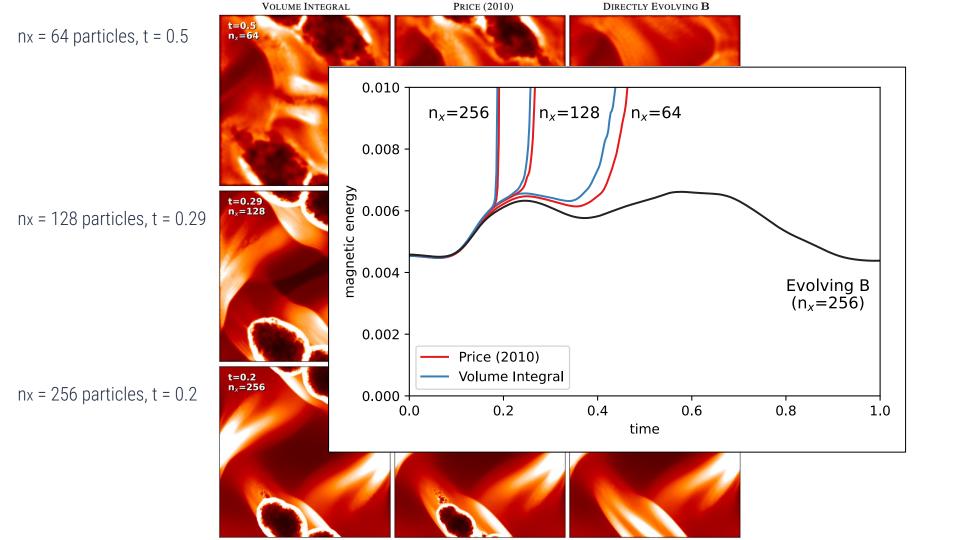
$$\begin{aligned} \frac{\mathrm{d}A_a^i}{\mathrm{d}t} = & \frac{A_a^j}{\Omega_a \rho_a} \sum_b m_b \left(v_a^j - v_b^j \right) \frac{\partial W_{ab}(h_a)}{\partial x_a^i} \\ &+ \frac{1}{\Omega_a \rho_a} \sum_b m_b \left(A_a^i - A_b^i \right) \left[(v_a^j - v_b^j) \frac{\partial W_{ab}(h_a)}{\partial x_a^j} \right] \end{aligned}$$



nx = 128 particles, t = 0.29

nx = 64 particles, t = 0.5

nx = 256 particles, t = 0.2



The integral vector potential formulation is still highly numerically unstable.

Why?

- One issue is that the magnetic field is evolved using **A**, but the equations of motion use **B**.
- This mismatch of variables does not conserve energy, leading to exponential energy growth and numerical instability.

Enforcing energy conservation can be achieved by solving for the equations of motion from the Lagrangian (specified in terms of A, not B).

$$\begin{aligned} \frac{\mathrm{d}v_{a}^{i}}{\mathrm{d}t} &= -\sum_{b} m_{b} \left[\frac{P_{a}}{\rho_{a}^{2}} + \frac{P_{b}}{\rho_{b}^{2}} \right] \frac{\partial W_{ab}}{\partial x_{a}^{i}} & \longrightarrow \text{ Pressure gradient} \\ &+ \frac{3}{2\mu_{0}} \sum_{b} m_{b} \left[\frac{B_{a}^{2}}{\rho_{a}^{2}} + \frac{B_{b}^{2}}{\rho_{b}^{2}} \right] \frac{\partial W_{ab}}{\partial x_{a}^{i}} \\ &- \frac{1}{\mu_{0}} \epsilon_{jkl} \sum_{b} m_{b} (A_{a}^{k} - A_{b}^{k}) \left[\frac{B_{a}^{j}}{\rho_{a}^{2}} + \frac{B_{b}^{j}}{\rho_{b}^{2}} \right] \frac{\partial^{2} W_{ab}}{\partial x_{a}^{i} \partial x_{a}^{l}} & \qquad \text{Equivalent to Price (2010) Formulation} \\ &- \sum_{b} m_{b} \left[\frac{A_{a}^{i}}{\rho_{a}^{2}} J_{a}^{k} + \frac{A_{b}^{i}}{\rho_{b}^{2}} J_{b}^{k} \right] \frac{\partial W_{ab}}{\partial x_{a}^{k}} \\ &- \sum_{b} m_{b} (A_{a}^{k} - A_{b}^{k}) \left[\frac{J_{a}^{k}}{\rho_{a}^{2}} + \frac{J_{b}^{k}}{\rho_{b}^{2}} \right] \frac{\partial W_{ab}}{\partial x_{a}^{i}} & \qquad \text{Additional term from integral approach} \end{aligned}$$

Most problematic is that the equations of motion do not represent the MHD equations of motion in the continuum limit!

lacksim Continuum equations derive from ${f J} imes {f B}$ where $\,{f J}=
abla imes {f B}/\mu_0$

$$\frac{\mathrm{d}v^{i}}{\mathrm{d}t} = -\frac{1}{\rho}\frac{\partial P}{\partial x^{i}} + \frac{1}{\rho}\left[J^{j}\frac{\partial A^{j}}{\partial x^{i}} - J^{j}\frac{\partial A^{i}}{\partial x^{j}}\right]$$

The integral approach equations of motion are equivalent to (note the spurious factor of 3)

$$\frac{\mathrm{d}v^{i}}{\mathrm{d}t} = -\frac{1}{\rho}\frac{\partial P}{\partial x^{i}} + \frac{1}{\rho}\left[3J^{j}\frac{\partial A^{j}}{\partial x^{i}} - J^{j}\frac{\partial A^{i}}{\partial x^{j}}\right]$$



An integral approach was developed to model the magnetic vector potential.
Key results:

- A correction term to the Price (2010) vector potential evolution equation is introduced. Results are **not improved**.
- The conservative equations of motion were derived, which includes a correction term to the Price (2010) approach.
- ▷ These equations of motion **do not represent** the MHD equations.

A truly divergence-free SPMHD solution continues to remain elusive.

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