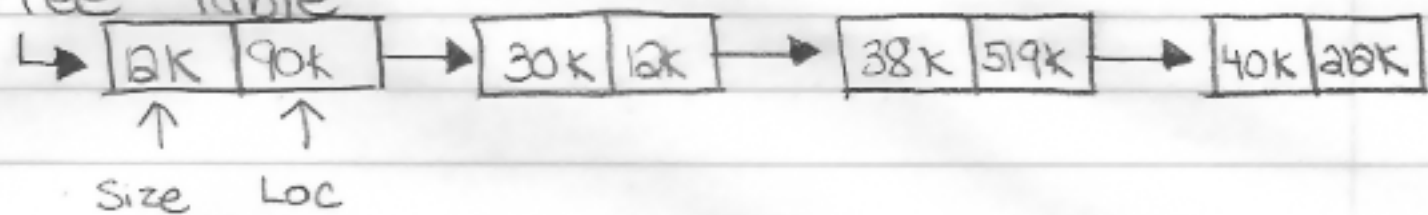


Recap

First-Fit Algorithm: The free table is kept sorted by length.

Best-Fit Algorithm: The free table is kept sorted by size.

eg. Free Table



i) Allocation It tries to find a free partition which fits the job's request as "tightly as possible" (best fit)

Adv: ① In best fit, if exact fit is possible, then that free partition is used.

⇒ Therefore allocation is NOT sensitive to the order of Job Request.

② The search for best fit is logarithmic (binary search) since the free table is kept sorted by size.

ii) Deallocation Here a neighboring free partition is sought.

Disadv: ① It may take a linear search in the worst case.

② Since we find the best possible fit, it leaves very thin free partitions which are big enough to satisfy a job's request.

### Best Fit + First Fit Problems

① Fragmentation

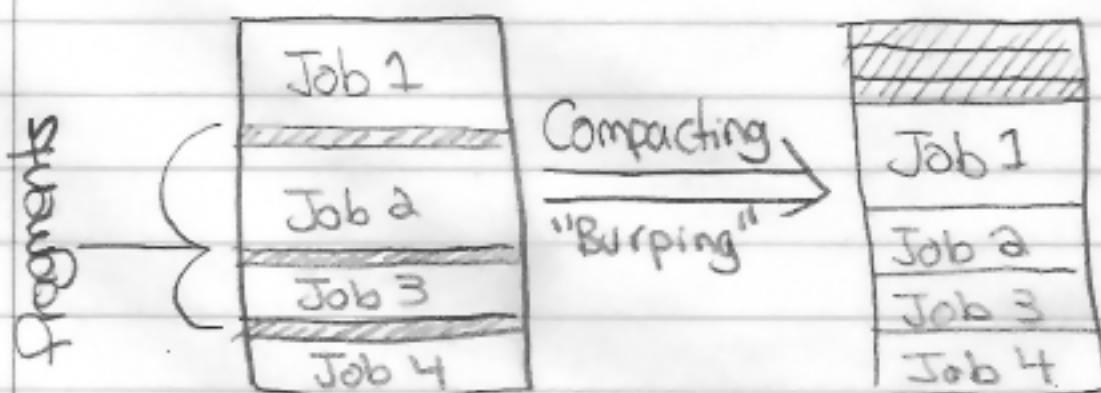
② If a job has to be swapped out temporarily, it has to be swapped in exact partition.

Next 1) Relocatable Dynamic Partition  
a) Paging

### Fragmentation

- Due to the allocation schemes in dynamic partitioning

- A large number of very small free spaces develop throughout the memory.
- Scattered and isolated, hence wasteful.
- Lesser degree multiprogrammable



Two differences due to early binding

- ① It is difficult to determine which datatypes are location sensitive.
- ② Even if it is possible to determine location sensitive datatypes, the content of the Jobs space will have to be modified.

Large Overhead.

Two Strategies:

- ① Data type tagging (B5500, 6500)
- ② Relocatable dynamic partition.

Relocatable Dynamic Partitioning Technique

- Binding between "local address" → "physical address" is done at the time of execution.
- The image of a job in memory looks the same as in the logical space.

Technique We maintain two privilege register:

- Base Register (B)
- Bound Register (b)

The base register gives the first address of the partition belonging to a job.

The bound register gives the last address of the partition belonging to a job.



Binding Let  $a_e$  be a logical address and  $a_p$  be the corresponding physical address.

$a_p = (a_e + B)$  if  $(a_e + B) \leq b$   
otherwise out-of-bound error.

→ Examples Contrasting IFC without relative dynamic partitions and IFC with relative dynamic partitions.

Machine M: | Address Machine  
PC - Prog. Counter  
B - Base register  
b - Bound register

- ADD X                     $Acc \leftarrow Acc + M[X]$
- STORE X                 $M[X] = Acc$
- BRANCH X               $PC \leftarrow X$

I) Without Dyn Relocation

$PC \leftarrow PC + 1$

$IR \leftarrow M[PC]$

$OP \leftarrow Dc(IR)$

$OPR_p \leftarrow IA(IR)$

Case Op:

ADD:  $ACC \leftarrow ACC + M[OPR_p]$

STORE:  $M[OPR_p] \leftarrow ACC$

BRANCH:  $PC \leftarrow OPR_p$

End Case

Loop

## II) With Relative Dynamic Partitions

$$PC_p \leftarrow (PC_e + B)^* + 1$$

$$IR \leftarrow M[PC_p]$$

$$OP \leftarrow DC(IR)$$

$$OPR_e \leftarrow IA(IR)$$

Case OP of:

ADD:  $ACC \leftarrow ACC + M[OPR_e + B]^*$

STORE:  $M[OPR_e + B]^* \leftarrow ACC$

BRANCH:

END

LOOP

\*We are not including in the script the out-of-bound test

## Hardware Level Implementation

