Localization: Part 5 Covariance Matrices and the Multivariate Normal Distribution

Computer Science 4766/6912

Department of Computer Science Memorial University of Newfoundland

July 11, 2018

To discuss the Kalman filter, we first need to discuss the **multivariate normal distribution**...

To discuss the Kalman filter, we first need to discuss the **multivariate normal distribution**...

To discuss the multivariate normal distribution, we first need to discuss **covariance matrices**...

To discuss the Kalman filter, we first need to discuss the **multivariate normal distribution**...

To discuss the multivariate normal distribution, we first need to discuss **covariance matrices**...

To discuss covariance matrices, we first need to review covariance...

The effect of one random variable on another is expressed by the **covariance** between the two variables

The effect of one random variable on another is expressed by the **covariance** between the two variables; This is defined as,

The effect of one random variable on another is expressed by the **covariance** between the two variables; This is defined as,

$$\sigma_{ij} = Cov(X_i, X_j) = E((X_i - \mu_{x_i})(X_j - \mu_{x_j}))$$

The effect of one random variable on another is expressed by the **covariance** between the two variables; This is defined as,

$$\sigma_{ij} = Cov(X_i, X_j) = E((X_i - \mu_{x_i})(X_j - \mu_{x_j}))$$

= $E(X_i X_j) - \mu_{X_i} \mu_{X_j}$

The effect of one random variable on another is expressed by the **covariance** between the two variables; This is defined as,

$$\sigma_{ij} = Cov(X_i, X_j) = E((X_i - \mu_{x_i})(X_j - \mu_{x_j}))$$

= $E(X_i X_j) - \mu_{X_i} \mu_{X_j}$

Unlike variance, covariance can be positive or negative:

The effect of one random variable on another is expressed by the **covariance** between the two variables; This is defined as,

$$\sigma_{ij} = Cov(X_i, X_j) = E((X_i - \mu_{x_i})(X_j - \mu_{x_j}))$$

= $E(X_i X_j) - \mu_{X_i} \mu_{X_j}$

Unlike variance, covariance can be positive or negative:

• Positive covariance implies that large values of X_i are associated with large values of X_i

The effect of one random variable on another is expressed by the **covariance** between the two variables; This is defined as,

$$\sigma_{ij} = Cov(X_i, X_j) = E((X_i - \mu_{x_i})(X_j - \mu_{x_j}))$$

= $E(X_i X_j) - \mu_{X_i} \mu_{X_j}$

Unlike variance, covariance can be positive or negative:

- Positive covariance implies that large values of X_i are associated with large values of X_i
- Negative covariance implies that large values of X_i are associated with small values of X_j , and vice versa

The effect of one random variable on another is expressed by the **covariance** between the two variables; This is defined as,

$$\sigma_{ij} = Cov(X_i, X_j) = E((X_i - \mu_{x_i})(X_j - \mu_{x_j}))$$

= $E(X_i X_j) - \mu_{X_i} \mu_{X_j}$

Unlike variance, covariance can be positive or negative:

- Positive covariance implies that large values of X_i are associated with large values of X_i
- Negative covariance implies that large values of X_i are associated with small values of X_j , and vice versa

The effect of one random variable on another is expressed by the **covariance** between the two variables; This is defined as,

$$\sigma_{ij} = Cov(X_i, X_j) = E((X_i - \mu_{x_i})(X_j - \mu_{x_j}))$$

= $E(X_i X_j) - \mu_{X_i} \mu_{X_j}$

Unlike variance, covariance can be positive or negative:

- Positive covariance implies that large values of X_i are associated with large values of X_i
- Negative covariance implies that large values of X_i are associated with small values of X_j , and vice versa

Related to covariance, is the **correlation coefficient**, which indicates a linear relationship between two random variables,

The effect of one random variable on another is expressed by the **covariance** between the two variables; This is defined as,

$$\sigma_{ij} = Cov(X_i, X_j) = E((X_i - \mu_{x_i})(X_j - \mu_{x_j}))$$

= $E(X_i X_j) - \mu_{X_i} \mu_{X_j}$

Unlike variance, covariance can be positive or negative:

- Positive covariance implies that large values of X_i are associated with large values of X_i
- Negative covariance implies that large values of X_i are associated with small values of X_j , and vice versa

Related to covariance, is the **correlation coefficient**, which indicates a linear relationship between two random variables,

$$\rho_{ij} = \frac{\sigma_{ij}}{\sigma_i \sigma_j}$$

The effect of one random variable on another is expressed by the **covariance** between the two variables; This is defined as,

$$\sigma_{ij} = Cov(X_i, X_j) = E((X_i - \mu_{x_i})(X_j - \mu_{x_j}))$$

= $E(X_i X_j) - \mu_{X_i} \mu_{X_j}$

Unlike variance, covariance can be positive or negative:

- Positive covariance implies that large values of X_i are associated with large values of X_i
- Negative covariance implies that large values of X_i are associated with small values of X_j , and vice versa

Related to covariance, is the **correlation coefficient**, which indicates a linear relationship between two random variables,

$$\rho_{ij} = \frac{\sigma_{ij}}{\sigma_i \sigma_j}$$

Variance can be considered a special case of covariance,

Variance can be considered a special case of covariance,

$$Var(X) = Cov(X, X)$$

Variance can be considered a special case of covariance,

$$Var(X) = Cov(X, X)$$

If two random variables are independent,

Variance can be considered a special case of covariance,

$$Var(X) = Cov(X, X)$$

If two random variables are independent,

$$Cov(X_1, X_2) = 0$$

Variance can be considered a special case of covariance,

$$Var(X) = Cov(X, X)$$

If two random variables are independent,

$$Cov(X_1,X_2)=0$$

Enough about covariance for now... What about covariance matrices? They come up more naturally if we look at functions of random variables...

• If a single random variable passes through a linear function, we can determine the expected value and variance of the output

• If a single random variable passes through a linear function, we can determine the expected value and variance of the output

$$\mu_y = E[a \cdot X + b] = a \cdot \mu_x + b$$

$$\mu_y = E[a \cdot X + b] = a \cdot \mu_x + b$$

$$\sigma_y^2 = E[(a \cdot X + b - \mu_y)^2]$$

$$\mu_y = E[a \cdot X + b] = a \cdot \mu_x + b$$

$$\sigma_y^2 = E[(a \cdot X + b - \mu_y)^2]$$

$$= a^2 \cdot \sigma_x^2$$

If a single random variable passes through a linear function, we can
determine the expected value and variance of the output
 Let y = f(x) = a · x + b

$$\mu_y = E[a \cdot X + b] = a \cdot \mu_x + b$$

$$\sigma_y^2 = E[(a \cdot X + b - \mu_y)^2]$$

$$= a^2 \cdot \sigma_x^2$$

What if the function involves some linear combination of random variables?

If a single random variable passes through a linear function, we can
determine the expected value and variance of the output
 Let y = f(x) = a · x + b

$$\mu_y = E[a \cdot X + b] = a \cdot \mu_x + b$$

$$\sigma_y^2 = E[(a \cdot X + b - \mu_y)^2]$$

$$= a^2 \cdot \sigma_x^2$$

What if the function involves some linear combination of random variables?

If a single random variable passes through a linear function, we can
determine the expected value and variance of the output
 Let v = f(x) = a · x + b

$$\mu_y = E[a \cdot X + b] = a \cdot \mu_x + b$$

$$\sigma_y^2 = E[(a \cdot X + b - \mu_y)^2]$$

$$= a^2 \cdot \sigma_x^2$$

• What if the function involves some linear combination of random variables?

e.g. Let
$$y = f(x_1, x_2) = a \cdot x_1 + b \cdot x_2$$

If a single random variable passes through a linear function, we can
determine the expected value and variance of the output
 Let v = f(x) = a · x + b

$$\mu_y = E[a \cdot X + b] = a \cdot \mu_x + b$$

$$\sigma_y^2 = E[(a \cdot X + b - \mu_y)^2]$$

$$= a^2 \cdot \sigma_x^2$$

• What if the function involves some linear combination of random variables?

e.g. Let
$$y = f(x_1, x_2) = a \cdot x_1 + b \cdot x_2$$

$$\mu_y = a \cdot \mu_{x_1} + b \cdot \mu_{x_2}$$

If a single random variable passes through a linear function, we can
determine the expected value and variance of the output
 Let v = f(x) = a · x + b

$$\mu_y = E[a \cdot X + b] = a \cdot \mu_x + b$$

$$\sigma_y^2 = E[(a \cdot X + b - \mu_y)^2]$$

$$= a^2 \cdot \sigma_x^2$$

• What if the function involves some linear combination of random variables?

e.g. Let
$$y = f(x_1, x_2) = a \cdot x_1 + b \cdot x_2$$

$$\mu_y = a \cdot \mu_{x_1} + b \cdot \mu_{x_2}$$

$$\sigma_y^2 = a^2 \cdot \sigma_{x_1}^2 + b^2 \cdot \sigma_{x_2}^2 + 2ab \cdot \sigma_{x_1 x_2}$$

If a single random variable passes through a linear function, we can
determine the expected value and variance of the output
 Let v = f(x) = a · x + b

$$\mu_y = E[a \cdot X + b] = a \cdot \mu_x + b$$

$$\sigma_y^2 = E[(a \cdot X + b - \mu_y)^2]$$

$$= a^2 \cdot \sigma_x^2$$

• What if the function involves some linear combination of random variables?

e.g. Let
$$y = f(x_1, x_2) = a \cdot x_1 + b \cdot x_2$$

$$\mu_y = a \cdot \mu_{x_1} + b \cdot \mu_{x_2}$$

$$\sigma_y^2 = a^2 \cdot \sigma_{x_1}^2 + b^2 \cdot \sigma_{x_2}^2 + 2ab \cdot \sigma_{x_1 x_2}$$

 What if we have multiple outputs? Things get complicated and it becomes helpful to introduce the...

Assume we have two linear functions, producing two outputs from two inputs,

Assume we have two linear functions, producing two outputs from two inputs,

$$y_1 = ax_1 + bx_2$$
$$y_2 = cx_1 + dx_2$$

Assume we have two linear functions, producing two outputs from two inputs,

$$y_1 = ax_1 + bx_2$$

$$y_2 = cx_1 + dx_2$$

We can introduce the vectors $\mathbf{y} = [y_1, y_2]^T$ and $\mathbf{x} = [x_1, x_2]^T$

Assume we have two linear functions, producing two outputs from two inputs,

$$y_1 = ax_1 + bx_2$$

$$y_2 = cx_1 + dx_2$$

We can introduce the vectors $\mathbf{y} = [y_1, y_2]^T$ and $\mathbf{x} = [x_1, x_2]^T$; The system can now be represented in matrix notation,

Assume we have two linear functions, producing two outputs from two inputs,

$$y_1 = ax_1 + bx_2$$

$$y_2 = cx_1 + dx_2$$

We can introduce the vectors $\mathbf{y} = [y_1, y_2]^T$ and $\mathbf{x} = [x_1, x_2]^T$; The system can now be represented in matrix notation,

$$\mathbf{y} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \mathbf{x}$$

Assume we have two linear functions, producing two outputs from two inputs,

$$y_1 = ax_1 + bx_2$$

$$y_2 = cx_1 + dx_2$$

We can introduce the vectors $\mathbf{y} = [y_1, y_2]^T$ and $\mathbf{x} = [x_1, x_2]^T$; The system can now be represented in matrix notation,

$$\mathbf{y} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \mathbf{x}$$
$$= A\mathbf{x}$$

Assume we have two linear functions, producing two outputs from two inputs.

$$y_1 = ax_1 + bx_2$$

$$y_2 = cx_1 + dx_2$$

We can introduce the vectors $\mathbf{y} = [y_1, y_2]^T$ and $\mathbf{x} = [x_1, x_2]^T$; The system can now be represented in matrix notation,

$$\mathbf{y} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \mathbf{x}$$
$$= A\mathbf{x}$$

It can easily be shown that,

Assume we have two linear functions, producing two outputs from two inputs,

$$y_1 = ax_1 + bx_2$$

$$y_2 = cx_1 + dx_2$$

We can introduce the vectors $\mathbf{y} = [y_1, y_2]^T$ and $\mathbf{x} = [x_1, x_2]^T$; The system can now be represented in matrix notation,

$$\mathbf{y} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \mathbf{x}$$
$$= A\mathbf{x}$$

It can easily be shown that,

$$\mu_{\mathbf{y}} = A\mu_{\mathbf{x}}$$

To talk about the uncertainty of the output, we must discuss uncertainty in the input—which is given by $\sigma_{x_1}^2$, $\sigma_{x_2}^2$, and $\sigma_{x_1x_2}$

$$\Sigma_{\mathbf{x}} = \left[\begin{array}{cc} \sigma_{x_1}^2 & \sigma_{x_1 x_2} \\ \sigma_{x_1 x_2} & \sigma_{x_2}^2 \end{array} \right]$$

$$\Sigma_{\mathbf{x}} = \left[\begin{array}{cc} \sigma_{\mathsf{x}_1}^2 & \sigma_{\mathsf{x}_1 \mathsf{x}_2} \\ \sigma_{\mathsf{x}_1 \mathsf{x}_2} & \sigma_{\mathsf{x}_2}^2 \end{array} \right]$$

(Note that the symbol Σ will be used to represent covariance matrices. It should be clear from the context whether a covariance matrix or a summation operator is intended.)

COMP 6912 (MUN) Localization July 11, 2018 7 / 1

$$\Sigma_{\mathbf{x}} = \left[\begin{array}{cc} \sigma_{\mathsf{x}_1}^2 & \sigma_{\mathsf{x}_1 \mathsf{x}_2} \\ \sigma_{\mathsf{x}_1 \mathsf{x}_2} & \sigma_{\mathsf{x}_2}^2 \end{array} \right]$$

(Note that the symbol Σ will be used to represent covariance matrices. It should be clear from the context whether a covariance matrix or a summation operator is intended.)

We now want to know $\Sigma_{\mathbf{v}}$ for our system

COMP 6912 (MUN) Localization July 11, 2018 7 / 1

$$\Sigma_{\mathbf{x}} = \left[\begin{array}{cc} \sigma_{\mathsf{x}_1}^2 & \sigma_{\mathsf{x}_1 \mathsf{x}_2} \\ \sigma_{\mathsf{x}_1 \mathsf{x}_2} & \sigma_{\mathsf{x}_2}^2 \end{array} \right]$$

(Note that the symbol Σ will be used to represent covariance matrices. It should be clear from the context whether a covariance matrix or a summation operator is intended.)

We now want to know $\Sigma_{\mathbf{v}}$ for our system; It turns out that this is given by,

Localization July 11, 2018

$$\Sigma_{\mathbf{x}} = \left[\begin{array}{cc} \sigma_{x_1}^2 & \sigma_{x_1 x_2} \\ \sigma_{x_1 x_2} & \sigma_{x_2}^2 \end{array} \right]$$

(Note that the symbol Σ will be used to represent covariance matrices. It should be clear from the context whether a covariance matrix or a summation operator is intended.)

We now want to know $\Sigma_{\mathbf{y}}$ for our system; It turns out that this is given by,

$$\Sigma_{\boldsymbol{y}} = A \Sigma_{\boldsymbol{x}} A^T$$

$$\Sigma_{\mathbf{x}} = \left[\begin{array}{cc} \sigma_{x_1}^2 & \sigma_{x_1 x_2} \\ \sigma_{x_1 x_2} & \sigma_{x_2}^2 \end{array} \right]$$

(Note that the symbol Σ will be used to represent covariance matrices. It should be clear from the context whether a covariance matrix or a summation operator is intended.)

We now want to know $\Sigma_{\mathbf{y}}$ for our system; It turns out that this is given by,

$$\Sigma_{\mathbf{y}} = A \Sigma_{\mathbf{x}} A^{T}$$

which is valid whenever y is a linear function of x (i.e. y = Ax)

COMP 6912 (MUN) Localization July 11, 2018 7 / 12

$$\Sigma_{\mathbf{x}} = \begin{bmatrix} \sigma_{x_1}^2 & \sigma_{x_1, x_2} & \cdots & \sigma_{x_1, x_n} \\ \sigma_{x_2, x_1} & \sigma_{x_2}^2 & \cdots & \sigma_{x_2, x_n} \\ \vdots & \vdots & & \vdots \\ \sigma_{x_n, x_1} & \sigma_{x_n, x_2} & \cdots & \sigma_{x_n}^2 \end{bmatrix}$$

$$\Sigma_{\mathbf{x}} = \begin{bmatrix} \sigma_{x_1}^2 & \sigma_{x_1, x_2} & \cdots & \sigma_{x_1, x_n} \\ \sigma_{x_2, x_1} & \sigma_{x_2}^2 & \cdots & \sigma_{x_2, x_n} \\ \vdots & \vdots & & \vdots \\ \sigma_{x_n, x_1} & \sigma_{x_n, x_2} & \cdots & \sigma_{x_n}^2 \end{bmatrix}$$

The formal definition of a covariance matrix is equivalent to the definition of covariance extended to vectors,

$$\Sigma_{\mathbf{x}} = \begin{bmatrix} \sigma_{x_1}^2 & \sigma_{x_1, x_2} & \cdots & \sigma_{x_1, x_n} \\ \sigma_{x_2, x_1} & \sigma_{x_2}^2 & \cdots & \sigma_{x_2, x_n} \\ \vdots & \vdots & & \vdots \\ \sigma_{x_n, x_1} & \sigma_{x_n, x_2} & \cdots & \sigma_{x_n}^2 \end{bmatrix}$$

The formal definition of a covariance matrix is equivalent to the definition of covariance extended to vectors,

$$\Sigma = E\left[(x - E[x])(x - E[x])^{T}\right]$$

$$\Sigma_{\mathbf{x}} = \begin{bmatrix} \sigma_{x_1}^2 & \sigma_{x_1, x_2} & \cdots & \sigma_{x_1, x_n} \\ \sigma_{x_2, x_1} & \sigma_{x_2}^2 & \cdots & \sigma_{x_2, x_n} \\ \vdots & \vdots & & \vdots \\ \sigma_{x_n, x_1} & \sigma_{x_n, x_2} & \cdots & \sigma_{x_n}^2 \end{bmatrix}$$

The formal definition of a covariance matrix is equivalent to the definition of covariance extended to vectors.

$$\Sigma = E\left[(x - E[x])(x - E[x])^T\right]$$

Covariance matrices have a number of special properties: square, symmetric, positive semidefinite

COMP 6912 (MUN) Localization July 11, 2018 8 / 12

• We are all now familiar with the definition of a 1-D Normal p.d.f.

• We are all now familiar with the definition of a 1-D Normal p.d.f.

We are all now familiar with the definition of a 1-D Normal p.d.f.

$$p(x) = (2\pi\sigma^2)^{-\frac{1}{2}} \exp\left\{-\frac{1}{2}\frac{(x-\mu)^2}{\sigma^2}\right\}$$

• We are all now familiar with the definition of a 1-D Normal p.d.f.

$$p(x) = (2\pi\sigma^2)^{-\frac{1}{2}} \exp\left\{-\frac{1}{2}\frac{(x-\mu)^2}{\sigma^2}\right\}$$

• If x is a n-dimensional vector then the multivariate Normal p.d.f. is

COMP 6912 (MUN) Localization July 11, 2018 9 / 12

• We are all now familiar with the definition of a 1-D Normal p.d.f.

$$p(x) = (2\pi\sigma^2)^{-\frac{1}{2}} \exp\left\{-\frac{1}{2}\frac{(x-\mu)^2}{\sigma^2}\right\}$$

• If x is a n-dimensional vector then the multivariate Normal p.d.f. is

COMP 6912 (MUN) Localization July 11, 2018 9 / 12

• We are all now familiar with the definition of a 1-D Normal p.d.f.

$$p(x) = (2\pi\sigma^2)^{-\frac{1}{2}} \exp\left\{-\frac{1}{2}\frac{(x-\mu)^2}{\sigma^2}\right\}$$

• If x is a n-dimensional vector then the multivariate Normal p.d.f. is

$$p(x) = \det (2\pi \Sigma)^{-\frac{1}{2}} \exp \left\{ -\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right\}$$

COMP 6912 (MUN) Localization July 11, 2018 9 / 12

• We are all now familiar with the definition of a 1-D Normal p.d.f.

$$p(x) = (2\pi\sigma^2)^{-\frac{1}{2}} \exp\left\{-\frac{1}{2} \frac{(x-\mu)^2}{\sigma^2}\right\}$$

• If x is a n-dimensional vector then the multivariate Normal p.d.f. is

$$p(x) = \det (2\pi \Sigma)^{-\frac{1}{2}} \exp \left\{ -\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right\}$$

ullet The mean μ is now a vector of size n

• We are all now familiar with the definition of a 1-D Normal p.d.f.

$$p(x) = (2\pi\sigma^2)^{-\frac{1}{2}} \exp\left\{-\frac{1}{2} \frac{(x-\mu)^2}{\sigma^2}\right\}$$

• If x is a n-dimensional vector then the multivariate Normal p.d.f. is

$$p(x) = \det (2\pi \Sigma)^{-\frac{1}{2}} \exp \left\{ -\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right\}$$

- The mean μ is now a vector of size n
- The variance σ^2 is now the covariance matrix Σ , which is a square matrix of size $n \times n$

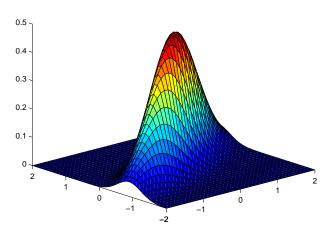
COMP 6912 (MUN) Localization July 11, 2018

The following is a 2-D normal distribution with $\mu = [0,0]^T$ and $\begin{bmatrix} 0.9 & 0.4 \end{bmatrix}$

$$\Sigma = \left[\begin{array}{cc} 0.9 & 0.4 \\ 0.4 & 0.3 \end{array} \right]$$

The following is a 2-D normal distribution with $\mu = [0,0]^T$ and _ _ _ [0.9 0.4]

$$\Sigma = \begin{bmatrix} 0.9 & 0.4 \\ 0.4 & 0.3 \end{bmatrix}$$



$$p(x) = \det(2\pi\Sigma)^{-\frac{1}{2}} \exp\left\{-\frac{1}{2}(x-\mu)^T\Sigma^{-1}(x-\mu)\right\}$$

$$p(x) = \det(2\pi\Sigma)^{-\frac{1}{2}} \exp\left\{-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)\right\}$$

For some values of x we get the same probability

$$p(x) = \det (2\pi \Sigma)^{-\frac{1}{2}} \exp \left\{ -\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right\}$$

For some values of x we get the same probability; In particular, when the expression $(x - \mu)^T \Sigma^{-1} (x - \mu)$ is constant we get a curve of constant probability

COMP 6912 (MUN) Localization July 11, 2018 11 / 12

$$p(x) = \det (2\pi \Sigma)^{-\frac{1}{2}} \exp \left\{ -\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right\}$$

For some values of x we get the same probability; In particular, when the expression $(x - \mu)^T \Sigma^{-1} (x - \mu)$ is constant we get a curve of constant probability; What curve

COMP 6912 (MUN) Localization July 11, 2018 11 / 12

$$p(x) = \det (2\pi \Sigma)^{-\frac{1}{2}} \exp \left\{ -\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right\}$$

For some values of x we get the same probability; In particular, when the expression $(x - \mu)^T \Sigma^{-1} (x - \mu)$ is constant we get a curve of constant probability; What curve? Define a constant c^2 as follows (shown in 2-D but works in higher dimensions as well),

$$p(x) = \det (2\pi \Sigma)^{-\frac{1}{2}} \exp \left\{ -\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right\}$$

For some values of x we get the same probability; In particular, when the expression $(x - \mu)^T \Sigma^{-1} (x - \mu)$ is constant we get a curve of constant probability; What curve? Define a constant c^2 as follows (shown in 2-D but works in higher dimensions as well),

$$\begin{bmatrix} x_1, y_1 \end{bmatrix} \begin{bmatrix} a & b \\ b & d \end{bmatrix} \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = c^2$$

where $[x_1, y_1]^T = (x - \mu)$ and the matrix in the middle is Σ^{-1}

Localization July 11, 2018 11 / 12

$$p(x) = \det (2\pi \Sigma)^{-\frac{1}{2}} \exp \left\{ -\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right\}$$

For some values of x we get the same probability; In particular, when the expression $(x - \mu)^T \Sigma^{-1} (x - \mu)$ is constant we get a curve of constant probability; What curve? Define a constant c^2 as follows (shown in 2-D but works in higher dimensions as well),

$$\begin{bmatrix} x_1, y_1 \end{bmatrix} \begin{bmatrix} a & b \\ b & d \end{bmatrix} \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = c^2$$

where $[x_1, y_1]^T = (x - \mu)$ and the matrix in the middle is Σ^{-1} . This can be expanded to obtain,

Localization July 11, 2018 11 / 12

$$p(x) = \det (2\pi \Sigma)^{-\frac{1}{2}} \exp \left\{ -\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right\}$$

For some values of x we get the same probability; In particular, when the expression $(x-\mu)^T \Sigma^{-1} (x-\mu)$ is constant we get a curve of constant probability; What curve? Define a constant c^2 as follows (shown in 2-D but works in higher dimensions as well),

$$\begin{bmatrix} x_1, y_1 \end{bmatrix} \begin{bmatrix} a & b \\ b & d \end{bmatrix} \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = c^2$$

where $[x_1, y_1]^T = (x - \mu)$ and the matrix in the middle is Σ^{-1} . This can be expanded to obtain,

$$ax_1^2 + 2bx_1y_1 + dy_1^2 = c^2$$

COMP 6912 (MUN) Localization July 11, 2018

11 / 12

$$p(x) = \det (2\pi \Sigma)^{-\frac{1}{2}} \exp \left\{ -\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right\}$$

For some values of x we get the same probability; In particular, when the expression $(x - \mu)^T \Sigma^{-1} (x - \mu)$ is constant we get a curve of constant probability; What curve? Define a constant c^2 as follows (shown in 2-D but works in higher dimensions as well),

$$\begin{bmatrix} x_1, y_1 \end{bmatrix} \begin{bmatrix} a & b \\ b & d \end{bmatrix} \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = c^2$$

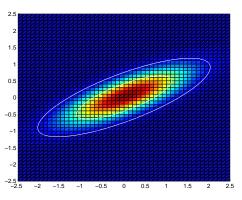
where $[x_1, y_1]^T = (x - \mu)$ and the matrix in the middle is Σ^{-1} . This can be expanded to obtain,

$$ax_1^2 + 2bx_1y_1 + dy_1^2 = c^2$$

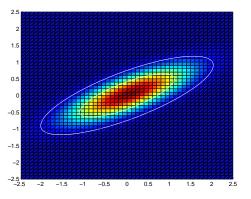
which is the equation of an ellipse.

An ellipse with $\alpha = 0.1$ is known as a 90% confidence ellipse,

An ellipse with $\alpha = 0.1$ is known as a 90% confidence ellipse,



An ellipse with $\alpha = 0.1$ is known as a 90% confidence ellipse,



The smaller ellipse is the 50% confidence ellipse, while the larger is the 90% confidence ellipse